

# **A Multi-Objective Sub-Domain Optimization Algorithm for Sensor Placement in Water Distribution Systems**

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# Background:

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- **Battle of Water Sensor Network (BWSN) session hosted by the University of Cincinnati (2006).**
- **Two water distribution systems were analyzed to place a finite number of sensors at a large number of potential locations.**
- **Four criteria for the evaluation of the performance of the design.**
  - **Min. Expected time of detection:  $Z_1$**
  - **Min. Expected population affected prior to detection:  $Z_2$**
  - **Min. Expected volume of contaminated water prior to detection:  $Z_3$**
  - **Max. Detection likelihood or reliability:  $Z_4$**



# Background:

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- **Several Algorithms were proposed:**

- Optimization based on single objective(s)
- Optimization based on multi-objectives

- **Solutions procedures used were also varied:**

- Enumeration
- Integer programming
- Heuristic methods
- Pareto front analysis (Non-dominated Sorting Algorithms).



# Background:

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## ➤ Some CHALLENGES:

- Computational efficiency;
- Computational memory requirements;
- Applicability to the solution of large scale systems; and,
- The question of how to handle the non-detects in this analysis?

} Sub-domain method

} Effects?



# Mathematical Model:

➤ Multi-objective optimization model:

$$f_1 = \text{minimize} \left\{ \frac{1}{N_s} \sum_{s=1}^{N_s} t_d^s(X) \right\}$$

$$f_2 = \text{minimize} \left\{ \frac{1}{N_s} \sum_{s=1}^{N_s} \sum_{i=1}^N \sum_{t=t_s^{in}}^{t_d^s(X)} V_i^s \right\}$$

$$f_3 = \text{maximize} \left\{ \frac{1}{N_s} \sum_{s=1}^{N_s} d_s(X) \right\}$$

$$\text{subject to} \quad \sum x_i = M$$

where

$$X = [x_1, x_2, \dots, x_n]^T$$

$$x_i = \{0, 1\}$$

$M$ : given number of sensors.

$n$ : # candidate junctions.

$N$ : # of junctions in WDS.

$N_s$ : # of scenarios.

$V_i(t)$ : Contaminated water Vol.

$d_s$ :  $\{0, 1\}$  detection parameter



# Sub-domain Solution Algorithm:

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- ◆ Total combinations of  $n$  junctions and  $k$  sensors:

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}$$

- ◆ Examples

Candidate junctions = 129

Sensor = 5

Total combinations = 275,234,400

Candidate junctions = 30

Sensor = 5

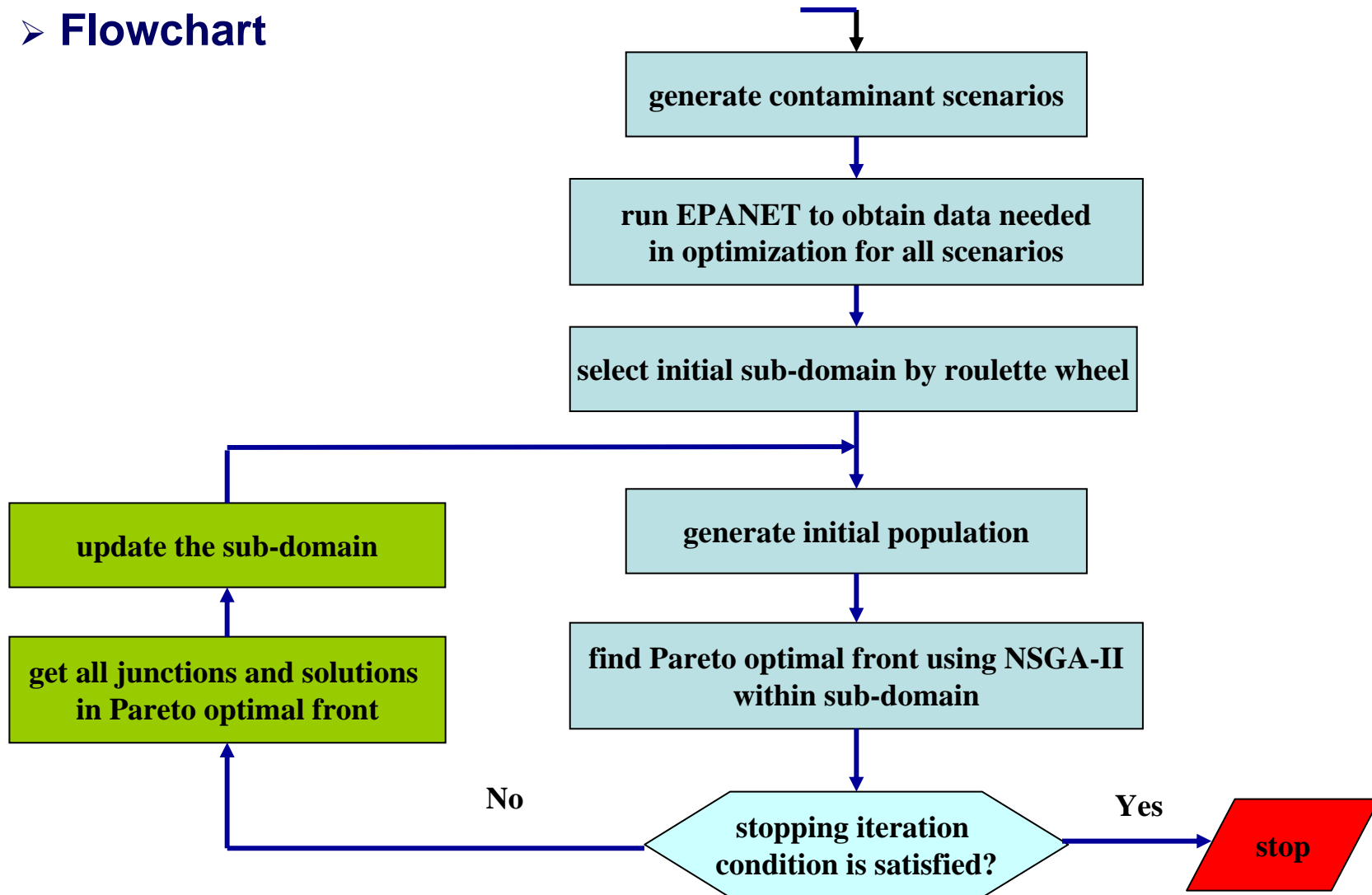
Total combinations = 142,506

$$Ratio = \frac{142,506}{275,234,400} = 0.05\%$$



# Sub-domain Solution Algorithm:

## ➤ Flowchart



# Sub-domain Solution Algorithm:

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## ➤ Remarks

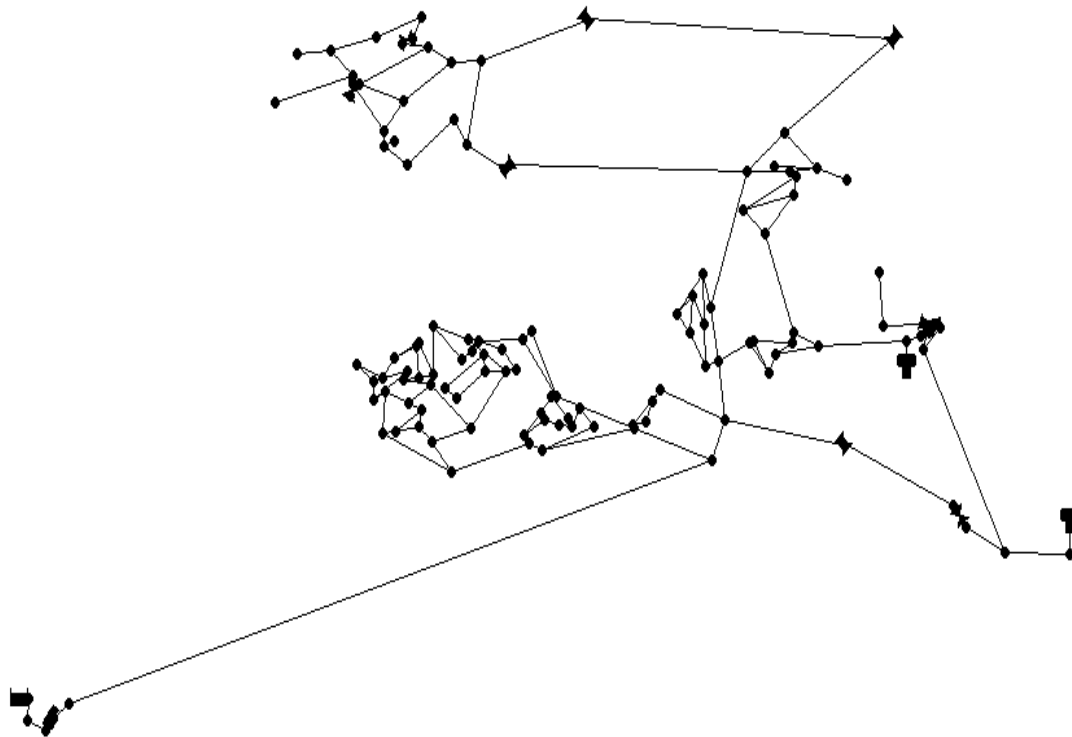
- Initial junctions are selected based on order of importance and roulette wheel method.
- Non-dominated sorting genetic algorithm (NSGA-II) works within reduced subsets of junctions (sub-domain).
- All junctions in Pareto optimal front directly enter the sub-domain in next iteration.
- Additional junctions will fill the remaining slots based on the order of importance at some probability using the roulette wheel method.
- Maximum iterations or same Pareto optimal fronts obtained in two consecutive iterations is chosen as stopping criterion.
- All junctions are cycled through the sub-domain based on some probability.





# Numerical Applications:

## ➤ Water Distribution System 1



- ◆ 129 junctions
- ◆ 169 pipes
- ◆ A reservoir
- ◆ 2 storage tanks
- ◆ 2 pumping stations



# Numerical Applications:

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## ➤ Water Distribution System 1

### ➤ Parameters:

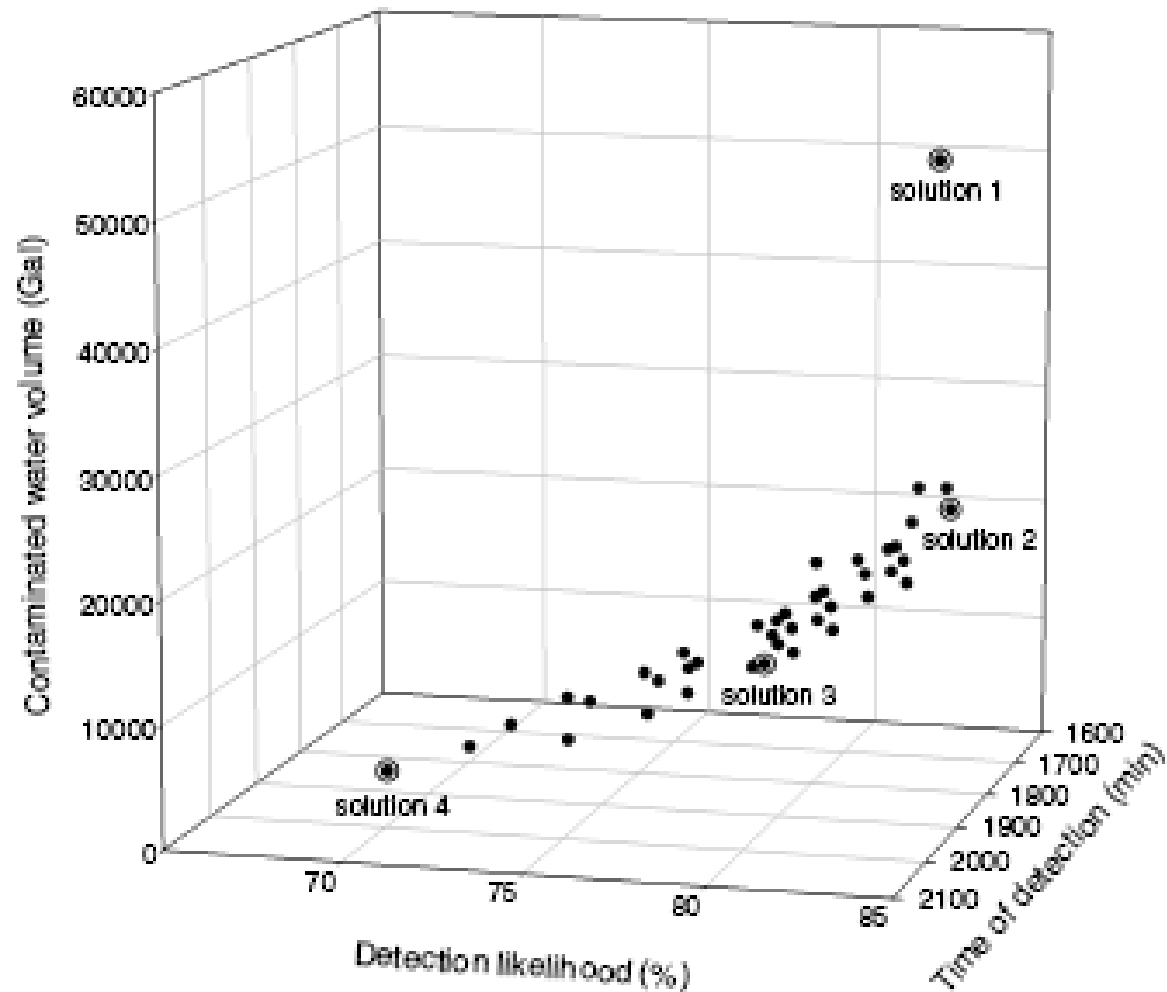
- Five sensors are placed.
  - Scenarios in optimization: 20 contamination scenarios for each junction resulting in total scenarios of 2580.
  - 30 candidate junctions in each sub-domain.
  - Maximum number of iterations is chosen as 20.
  - Scenarios in evaluation: Same number scenarios but generated independently.
  - Evaluation of the outcome is done by an independent software used in BWSN 2006.
- 
- Time of detection for non-detected scenarios is set as length of duration as a penalty.



# Numerical Applications: (ND included in optimization)

## ➤ Water Distribution System 1

- **Case 1:** Three objectives are selected in optimization, none detects are considered.



# Numerical Applications: (ND Excluded in evaluation)

## ➤ Water Distribution System 1

### ➤ Case 1: Three objectives are selected in optimization

Solution	Junction ID	$Z_1$ (minutes)	$Z_2$	$Z_3$ (Gal)	$Z_4$ (%)
1	J10, J45, J83, J100, J126	1,263.4	672.5	43,065.1	83.80
2	J10, J45, J83, J100, J118	1,050.1	388.3	12,879.6	83.02
3	J10, J68, J83, J118, J122	919.1	301.8	5,416.5	78.49
4	J17, J49, J68, J83, J102	715.5	148.3	2,780.6	70.16



where

$Z_1$ : expected time of detection,

$Z_2$ : expected population affected

$Z_3$  : expected volume contaminated,

$Z_4$ : detection likelihood

The results shown are for the 100<sup>th</sup> iteration.



# Numerical Applications:

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## ➤ Water Distribution System 1

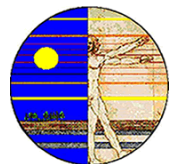
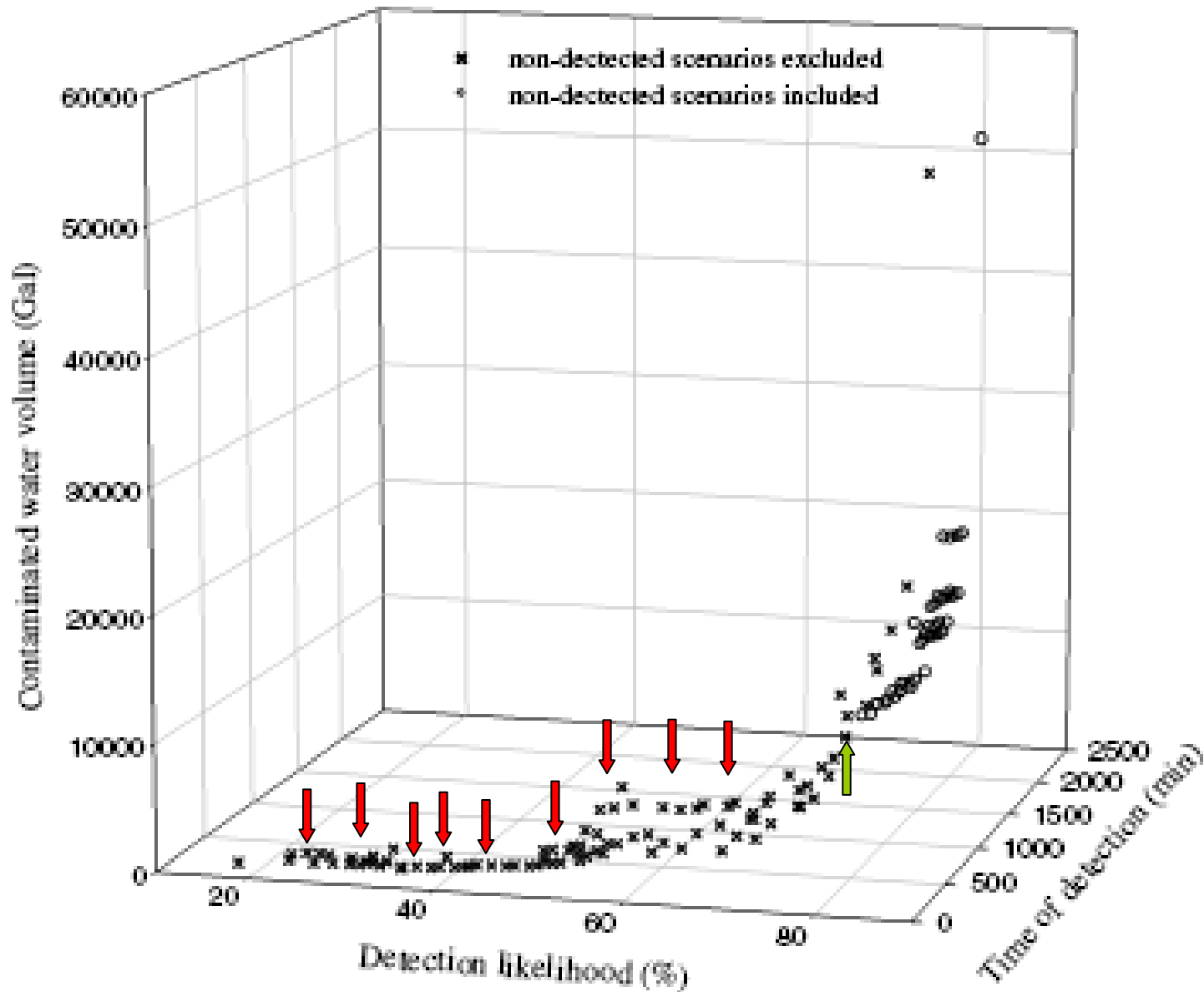
➤ The same as Case 1 three objectives are selected.

➤ The purpose is to analyze the effect of the non-detected scenarios on the Pareto optimal front.

➤ This application is identified as **(Case 3)**.



# Numerical Applications:



# **Numerical Applications:** (ND excluded in calc. & eval.)

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## ➤ **Water Distribution System 1**

- **The previous problem has been solved by Preis and Ostfeld, 2006.**
- **They have used NSGA applied to the whole domain.**
- **In that study the minimization of the expected time of detection and maximization of detection likelihood were selected as design objectives.**
- **The non-detected scenarios were excluded in calculation of time of detection.**
- **This is a good test case to demonstrate the effectiveness and efficiency of the proposed algorithm and also the effect of non-detects on the solution.**

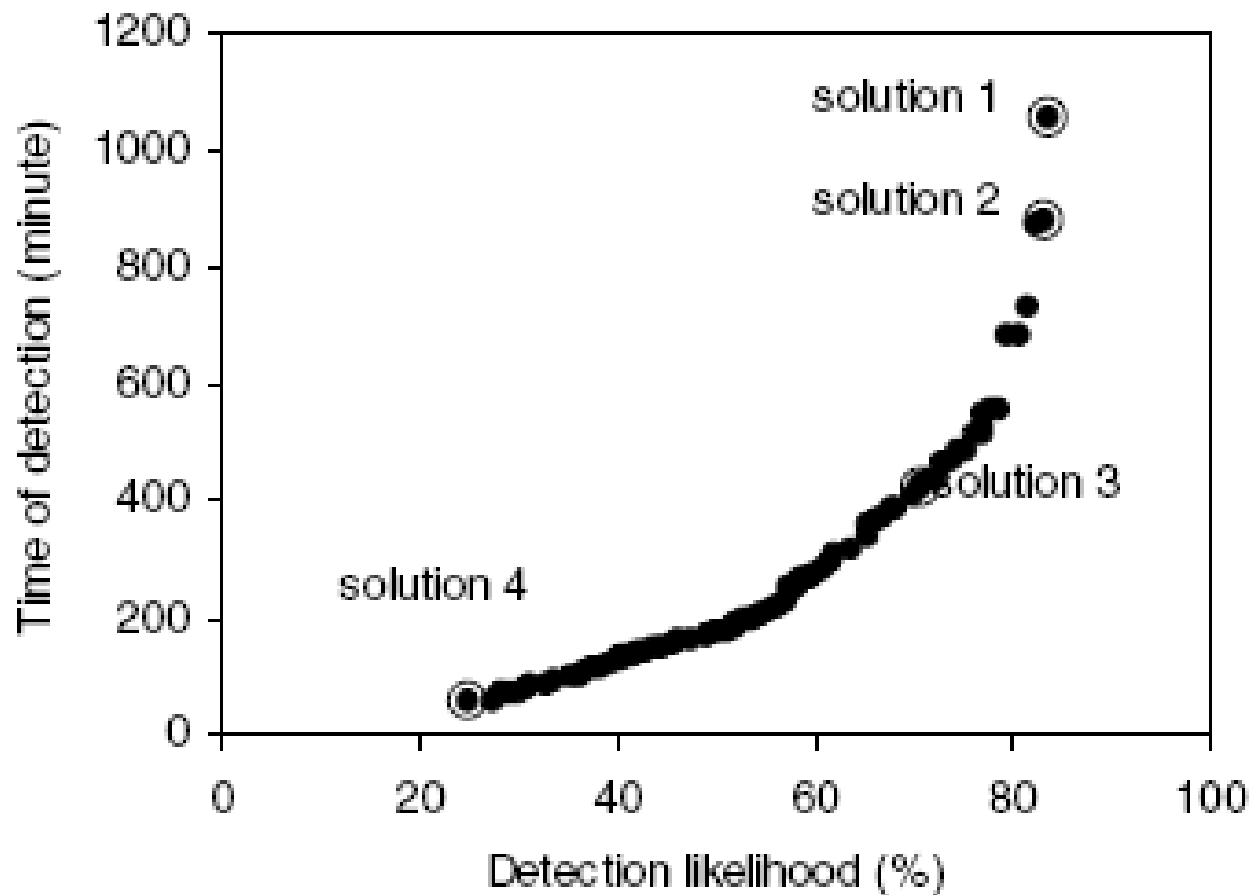
**(Case 2)**



# Numerical Applications: (ND excluded in calc. & eval.)

## ➤ Water Distribution System 1

- **Case 2:** Minimization of the expected time of detection and maximization of detection likelihood are selected as design objectives.
- The non-detected scenarios are excluded in calculation of time of detection for testing the effectiveness and efficiency of the algorithm





# Numerical Applications: (ND excluded in calc. & eval.)

## ➤ Water Distribution System 1

➤ **Case 2:** minimization of the expected time of detection and maximization of detection likelihood are selected as design objectives.

Solution	Junction ID	$Z_1$ (minutes)	$Z_2$	$Z_3$ (Gal)	$Z_4$ (%)
1	J10, J45, J83, J100, J126	1,263.4	672.5	43,065.1	83.80
2	J10, J45, J83, J100, J118	1,050.1	388.3	12,879.6	83.02
3	J21, J68, J83, J99, J118	597.4	190.2	2,695.5	70.70
4	J21, J31, J43, J58, J93	394.6	138.1	6,649.3	26.55



Solutions obtained by NSGA-II in Preis and Osfeld, 2006

Solution	Junction ID	$Z_1$ (minutes)	$Z_2$	$Z_3$ (Gal)	$Z_4$ (%)
1	J29, J30, J34, J43, J49	517.9	212.6	18,447.1	14.46
2	J21, J46, J68, J101, J116	436.1	154.8	7,106.6	47.56
3	J45, J70, J83, J101, J116	682.1	241.6	8,165.2	66.04



Solutions reported by NSGA-II in Preis and Osfeld, 2006 after 440 generations  
In this solution the reported results are obtained after 70 generations (3 iter/sub).



# Numerical Applications:

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## ➤ Water Distribution System 2



- ◆ 12,523 junctions
- ◆ 14,822 pipes
- ◆ 2 reservoirs
- ◆ 2 storage tanks
- ◆ 4 pumping stations



# Numerical Applications:

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## ➤ Water Distribution System 2

### ➤ Parameters

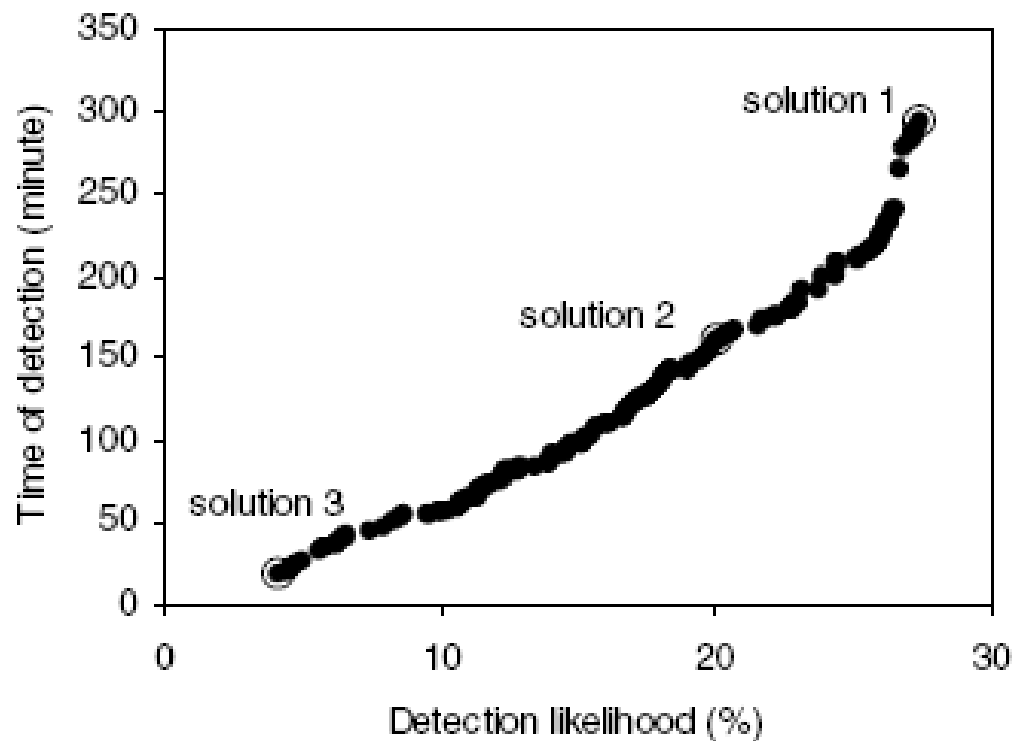
- Five sensors are placed
- Scenarios in optimization: 3000 contamination scenarios are randomly generated
- Scenarios in evaluation: same number scenarios but generated independently
- 100 candidate junctions in each sub-domain
- Maximum iterations is given as 50
- Evaluation software used in BWSN 2006



# Numerical Applications: (ND excluded in calc. & eval.)

## ➤ Water Distribution System 2

- Minimization of the expected time of detection and maximization of detection likelihood are selected as design objectives.
- The non-detected scenarios are excluded in calculation of time of detection for testing the effectiveness and efficiency of the algorithm



# Numerical Applications: (ND excluded in calc. & eval.)

## ➤ Water Distribution System 2

- Minimization of the expected time of detection and maximization of detection likelihood are selected as design objectives.

Solution	Junction ID	$Z_1$ (minutes)	$Z_2$	$Z_3$ (Gal)	$Z_4$ (%)
1	J1486, J3747, J4247, J8452, J10874	1,055.2	2,338.1	206,837.3	28.03
2	J1486, J3301, J4247, J4684, J10393	769.9	1865.0	122,546.8	17.33
3	J32, J4247, J4562, J4771, J13349	427.5	1,083.2	48,201.9	4.60

Solutions obtained by NSGA-II in Preis and Osfeld, 2006

Solution	Junction ID	$Z_1$ (minutes)	$Z_2$	$Z_3$ (Gal)	$Z_4$ (%)
1	J871, J1917, J2024, J4115, J4247	807.2	1,700.1	122,986.8	16.80
2	J336, J470, J690, J723, J913	522.97	1,486.0	72,446.9	3.03



# Conclusions:

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- **The multi-objective sub-domain optimization model proposed can be effectively used in the solution of design of water sensor network in large water distribution systems.**
- **The algorithm, based on NSGA-II and sub-domain, is an effective approach for solving multi-objective optimization model.**
- **Inclusion of non-detects into analysis algorithmically excludes most solutions on the Pareto front which may not be desirable solutions.**
- **Non-detected scenarios can be included in the calculation of objectives in both design and evaluation phases. Simulation duration time can be used for this as a penalty function to include the impact of the non-detected scenarios.**



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**Thank You.**

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