

Nodal Importance Concept for Computational Efficiency in Optimal Sensor Placement in Water Distribution Systems

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Disclaimer

- *The findings and conclusions in this presentation have not been formally disseminated by CDC or ATSDR and should not be construed to represent any agency determination or policy.*



Background & Motivation for Study

- Recent interest in protecting drinking water in water distribution systems (WDSs) in the event of terrorist attack by contaminant injection
- Human variables of uncertainty hinder definitive contaminant sensor placement in WDSs
- Methods documented to date
 - computationally-expensive algorithms
 - oversimplifying assumptions
 - inability for implementation on larger systems
- Method needed to increase efficiency of search for optimal placement schemes without compromising WDS protection.



Study Problem

➤ Objective

- Allocate contaminant sensors to WDS nodes in a computationally efficient manner to provide maximum WDS protection.

➤ Performance Measures

- Z_{time} = expected detection time (minimized)
- Z_{vol} = expected contaminated water volume (minimized)
- Z_{lik} = detection likelihood (maximized)

➤ Limiting Factor

- M = fixed number of sensors available

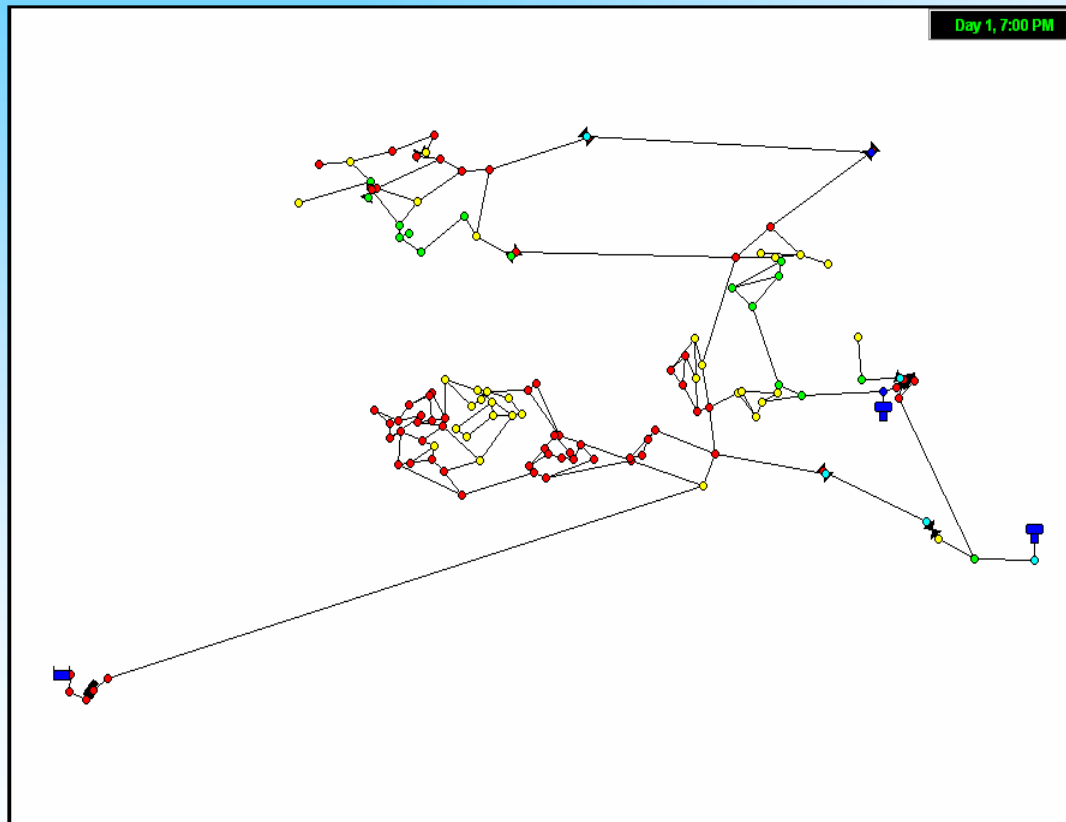
➤ Attack Scenario

- eligible injection node: any one node in WDS
- eligible injection time: any 5-minute multiple of first 1/4 of study period
- injection: constant mass flow of conservative contaminant



Study System

➤ BWSN Network 1 *



- 129 nodes (126 junctions, 2 tanks, 1 reservoir)
- 178 links (168 pipes, 2 pumps, 8 valves)
- localized flow behavior
- large variance in hydraulic demand (63% of junctions with demand)
- 96-hour study period



Nodal Importance Concept (1)

- Nodal Importance Defined
 - degree to which an individual WDS node should be considered as a candidate for sensor placement
 - related to potential on average for adverse effects to be experienced at an individual node under an unknown attack scenario
- Use of Concept
 - isolate a subset of “more important” nodes to confine search domain
 - test different combinations of subset nodes with optimization algorithm to find sensor placement scheme providing maximum protection
- Expected Advantages
 - better-performing sensor placement schemes
 - reduced computational runtimes



Nodal Importance Concept (2)

➤ Nodal Importance Function

$$f_{is} = \alpha_1 \frac{V_{is}^{cont}}{\max_i (V_{is}^{cont})} + \alpha_2 \left(\frac{T_s - t_{is}^d}{T_s} \right) D_{is}$$

V_{is}^{cont} = total contaminated volume associated with node i under scenario s assuming no contaminant detection at node i

t_{is}^d = time after injection during scenario s when contaminant is first present at node i (if not present at any time, $t_{is}^d = 2 \times$ study period duration)

T_s = time after injection at the end of study period for scenario s

$D_{is} = 1$ or 0 , indicating contaminant presence or absence, respectively, of contaminant at node i at any time during scenario s

α_1, α_2 : scalars in domain $[0, 1]$ ($\alpha_1 + \alpha_2 = 1$)



Nodal Importance Concept (3)

- Weighting of importance function terms
 - Use array of (α_1, α_2) schemes to capture nodes according to different protection preferences
 - $(\alpha_1, \alpha_2) = (1, 0), (0, 1), \& (1/2, 1/2)$ for this study
- Relative Importance

$$f_{is}^{rel} = \frac{f_{is}}{\max_i (f_{is})}$$

- Expected Relative Importance

$$F_i = \frac{1}{S} \sum_s f_{is}^{rel} \quad S = \text{number of Monte Carlo scenarios run}$$

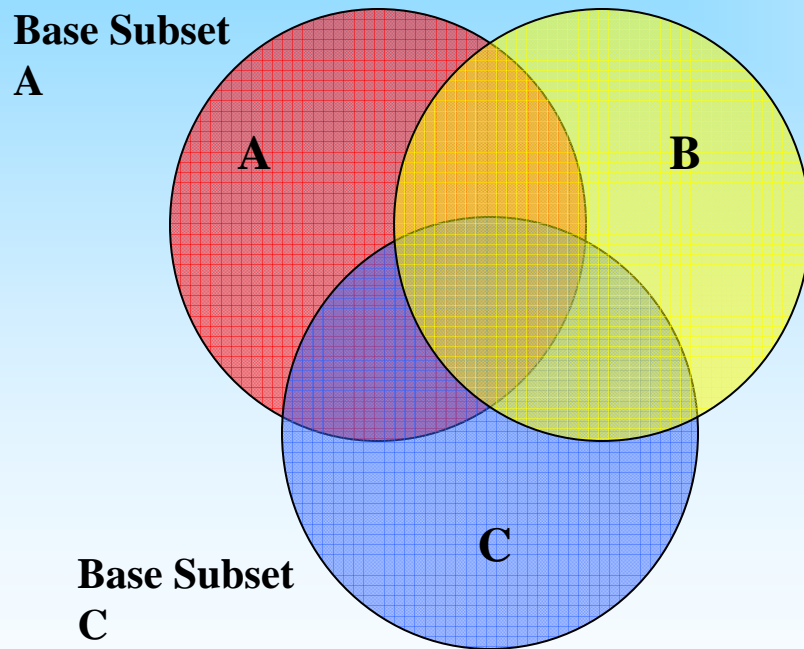
- Used to rank nodes for a particular (α_1, α_2) scheme



Subset Creation (1)

➤ Base Subsets to Total Subset

- each “base subset” of more-important nodes corresponds to a particular (α_1, α_2) scheme
- “total subset” is the union of all base subsets generated



$$(\alpha_1, \alpha_2)_A = (1, 0)$$

$$(\alpha_1, \alpha_2)_B = (0, 1)$$

$$(\alpha_1, \alpha_2)_C = (1/2, 1/2)$$

$$\text{Base Subset Size} = \text{size}(A) = \text{size}(B) = \text{size}(C)$$

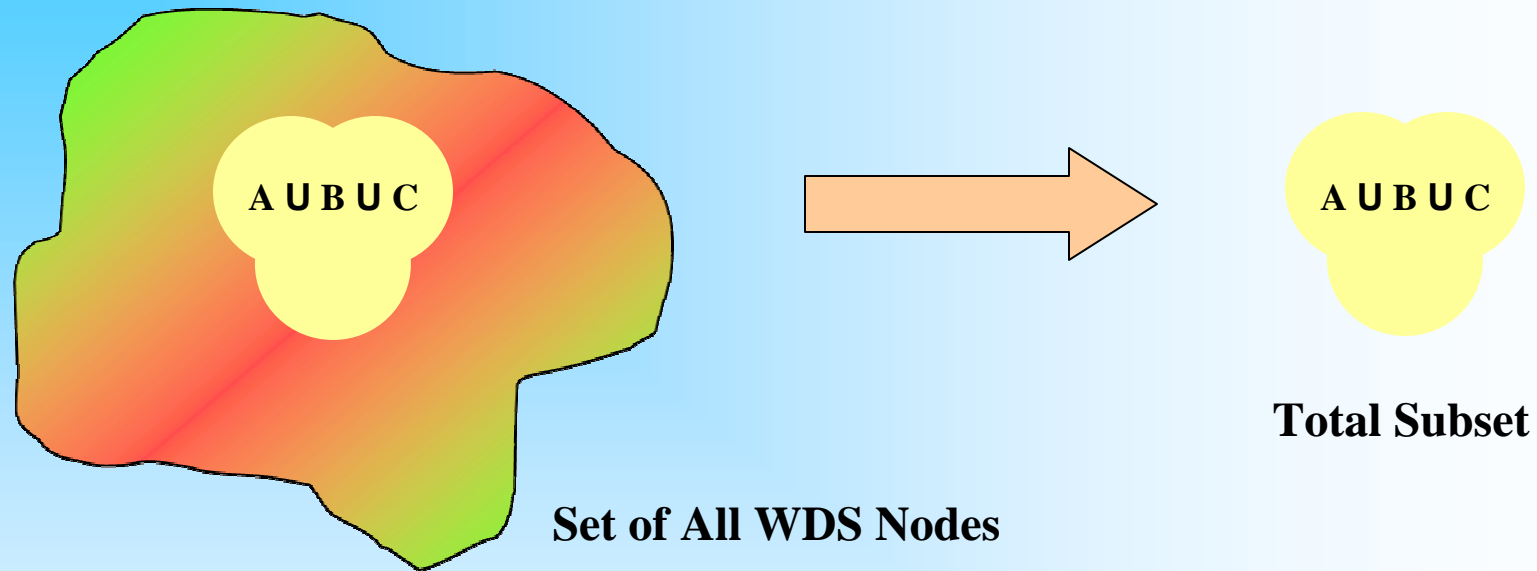
$$\text{Total Subset} = A \cup B \cup C$$

$$\text{Total Subset Size} = \text{size}(A \cup B \cup C)$$

$$\text{Base Subset Size} \leq \text{Total Subset Size} \leq (3 * \text{Base Subset Size})$$



Subset Creation (2)



- Only nodes in total subset tested for sensor placement
- The optimal subset: smallest subset that includes optimal nodes for sensor placement



Optimization (1)

➤ Program

$$\max Z_{comb} = \gamma_1 \frac{\max_s (t_s^d) - Z_{time}}{\max_s (t_s^d)} + \gamma_2 \frac{\max_s (V_s^{cont,d}) - Z_{vol}}{\max_s (V_s^{cont,d})} + \gamma_3 Z_{lik}$$

$$\text{s.t.} \quad \sum_{a=1}^A m_a = M \quad \forall \text{ all } a$$

$$m_a \in \{0,1\} \quad \forall \text{ all } a$$

t_s^d = time after attack when contaminant is first present under scenario s at any node i with an assigned sensor

$V_s^{cont,d}$ = total volume contaminated under s at all i until t_s^d

$m_a = 0$ or 1 , indicating the absence or presence, respectively, of a sensor at total subset node a

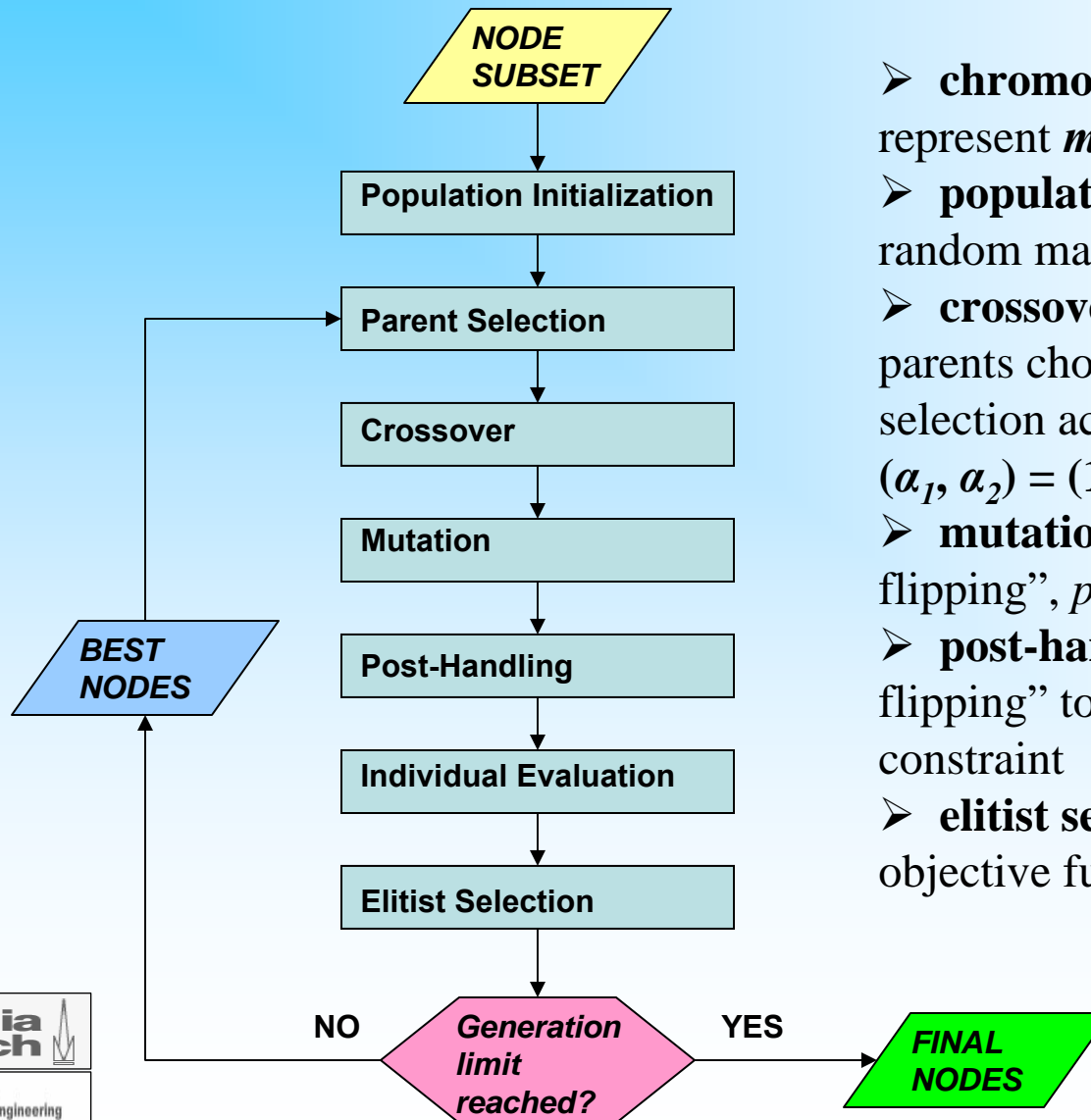
A = number of nodes in total subset

$\gamma_1, \gamma_2, \gamma_3$: scalars in the domain $[0, 1]$ ($\gamma_1 + \gamma_2 + \gamma_3 = 1$)



Optimization (2)

➤ “Simple” Genetic Algorithm



- **chromosome**: binary string; bits represent m_a values
- **population**: initialized in uniform, random manner
- **crossover**: one-point, $p_{cross} = 0.95$; parents chosen through roulette-wheel selection according to F_i values under $(\alpha_1, \alpha_2) = (1/2, 1/2)$
- **mutation**: uniform, random “bit-flipping”, $p_{mut} = 0.05$
- **post-handling**: uniform, random “bit-flipping” to satisfy sensor availability constraint
- **elitist selection**: according to objective function



Performance Testing (1)

- Decision Variables
 - variables kept constant
 - $M = 5$
 - $S = 3,000$
 - GA population size = 500
 - number of GA generations = 500
 - designated weighting schemes
 - $(\alpha_1, \alpha_2) = (1, 0), (0, 1), (1/2, 1/2)$
 - $(\gamma_1, \gamma_2, \gamma_3) = (1/4, 1/2, 1/4)$
 - subset size
 - critical variable for testing use of importance concept – allowed to vary
 - base subset size candidates: 5, 10, 20, 30, 40, 50
- Computational Runtimes
 - less than 1 hour for all tests employing nodal importance concept



Performance Testing (2)

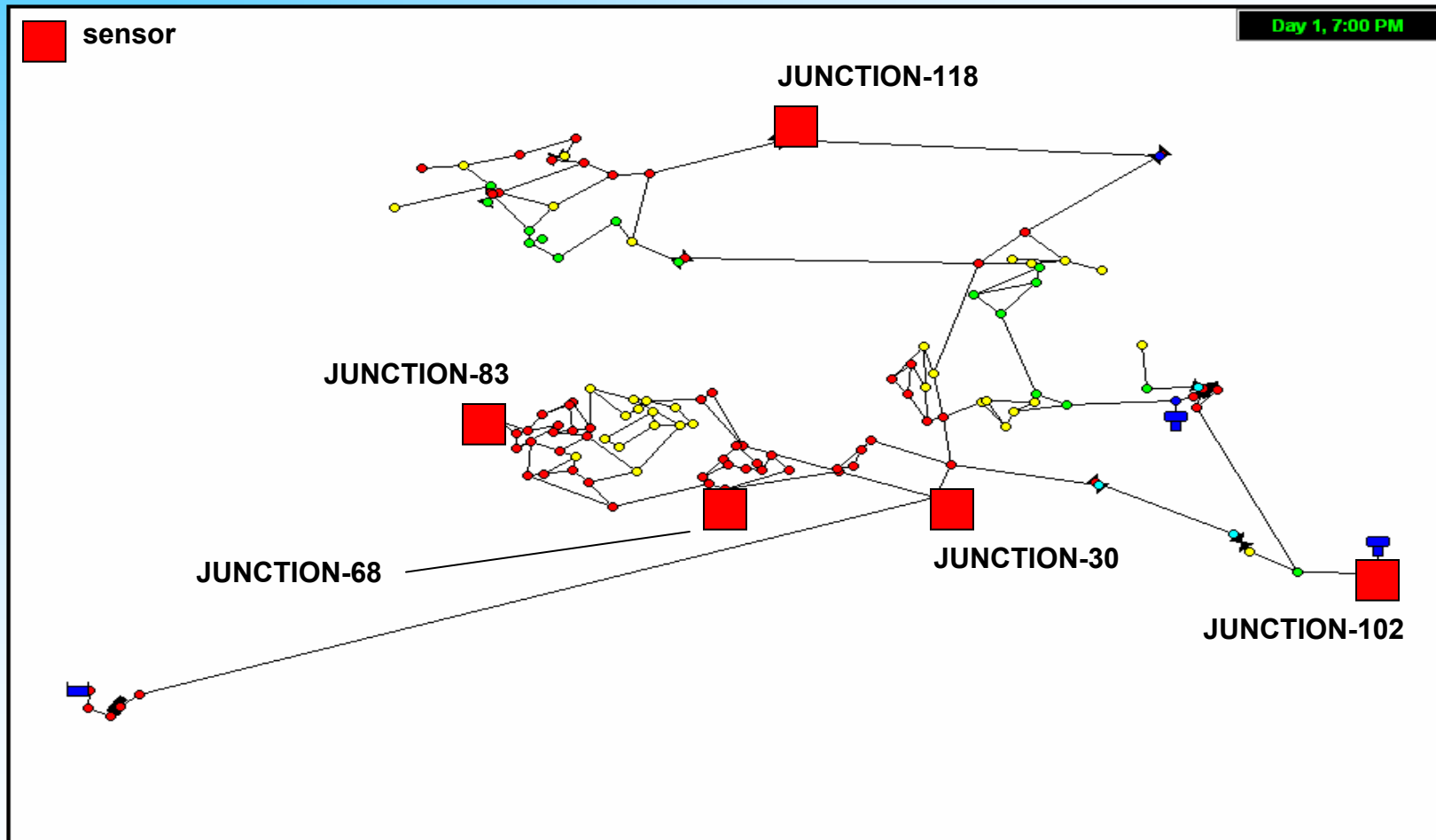
➤ Method Results

Method	Base Subset Size	Total Subset Size	Sensor Nodes (“JUNCTION-x”)	Z_{time} (min)	Z_{vol} (gal)	Z_{tik} (%)	Z_{comb} x 10 ²
random placement				7382	10994	37.6	20.1
GA-only		129	17, 49, 84, 100, 122	3783	2269	70.5	73.7
ranking-GA (a)	5	9	17, 30, 68, 83, 126	4162	3949	66.9	64.9
ranking-GA (b)	10	18	30, 68, 83, 102, 118	3686	1985	71.1	75.3
ranking-GA (c)	20	37	17, 68, 83, 100, 103	3272	2635	75.1	74.6
ranking-GA (d)	30	47	68, 83, 100, 102, 118	3034	3038	77.2	74.1
ranking-GA (e)	40	59	45, 68, 83, 103, 118	3236	2665	75.2	74.6
ranking-GA (f)	50	73	68, 83, 100, 103, 117	3222	2954	75.6	73.5



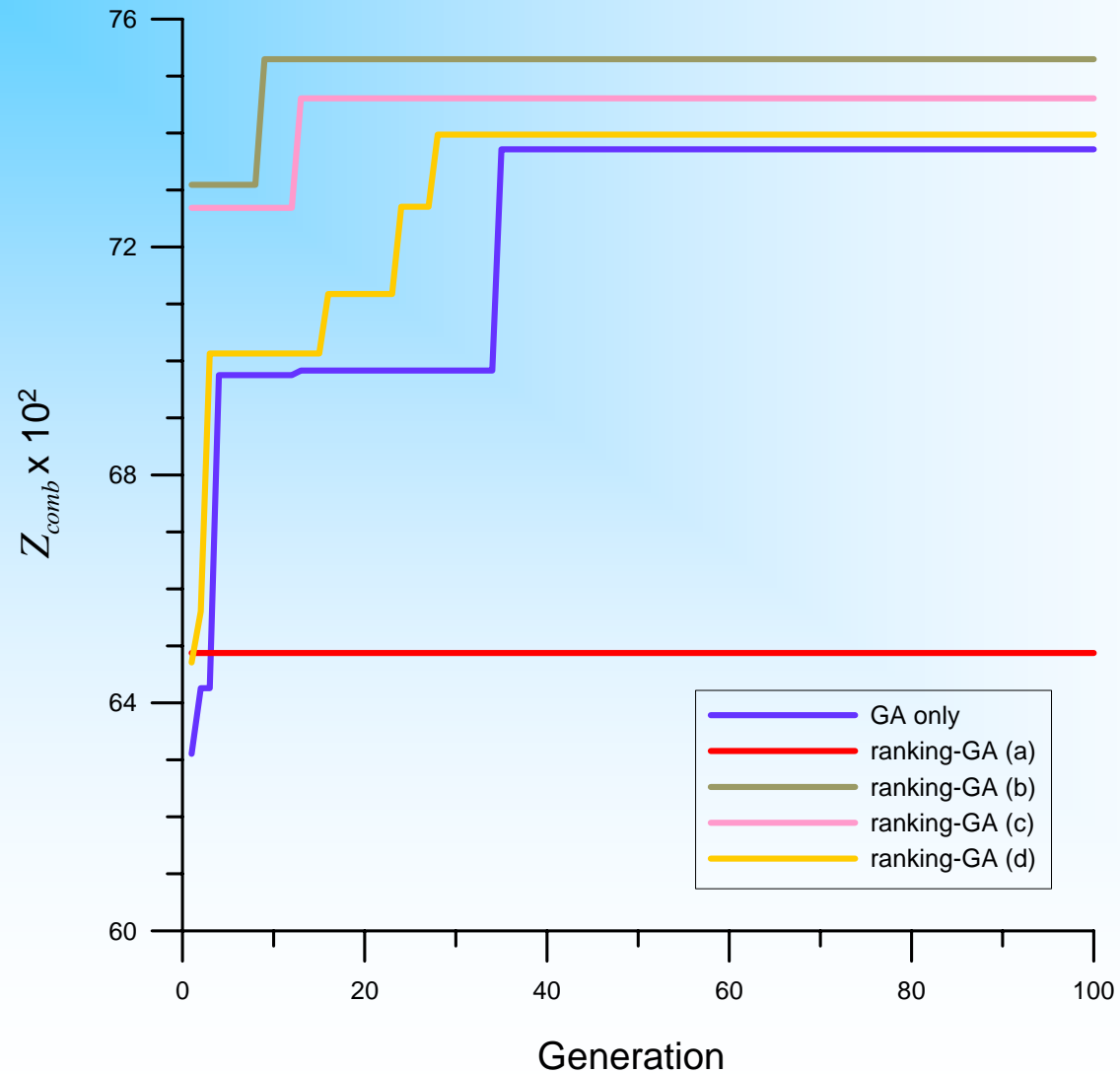
Performance Testing (3)

➤ Sensor Placement: Method “ranking-GA (b)”



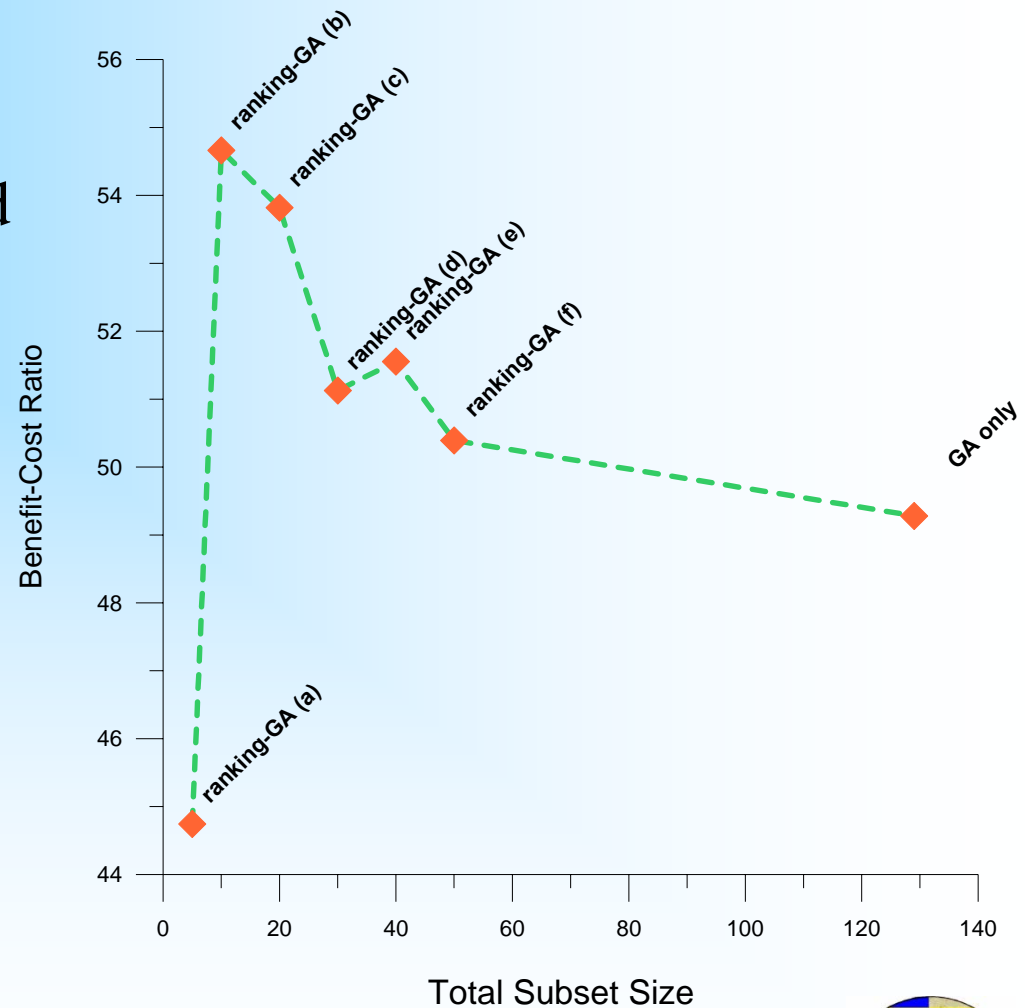
Performance Testing (4)

➤ Performance vs. GA Generation



Performance Testing (5)

- Benefit-Cost Ratios
 - Benefit: gained performance for method beyond baseline from random placement
 - B/C Ratio: benefit averaged over all scenarios up to GA generation of convergence for all methods



Observations & Conclusions

- Using nodal importance concept can lead to heightened efficiency in the optimization of contaminant sensor placement without compromising WDS protection goals.
- A subset of more-important nodes too small in size may not provide enough diversity for finding a sensor placement scheme of acceptably high performance.
- As the size of a subset increases toward the total number of WDS nodes, performance reaches a peak value then converges to a value resulting from optimization without using the importance concept.



Future Work

- Applying nodal importance concept to optimization of sensor placement in larger systems
- Resolving ambiguities
 - definitiveness of importance functions & corresponding variables
 - number of Monte Carlo scenarios to run
 - subset sizes
- Developing means of faster WDS simulation

